

Partial rigidity on \mathcal{S} -adic subshifts

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Joint work with A. Maass and S. Donoso.

Definition (X, \mathcal{X}, μ, T) is partially rigid if there exists $\delta > 0$ and a sequence $(N_n)_{n \in \mathbb{N}}$ such that

$$\liminf_{n \rightarrow \infty} \mu(A \cap T^{-N_n} A) \geq \delta \mu(A) \quad \text{for all } A \in \mathcal{X}$$

- $(N_n)_{n \in \mathbb{N}}$ is a *partial rigidity sequence*.
- δ is a *constant of partial rigidity* ($\delta > \gamma > 0$ is another constant of partial rigidity).

Special case: The system is **rigid** whenever $\delta = 1$, in that case

$$\lim_{n \rightarrow \infty} \mu(A \cap T^{-N_n} A) = \mu(A) \quad \text{for all } A \in \mathcal{X}.$$

Facts: Partially rigid systems are

- not mixing,
- zero entropy (Bruin, Karpel, Oprocha and Radinger 2025).

Examples:

- Equicontinuous systems are *rigid*
- Substitution subshifts are *partially rigid* (Dekking 1978)
- Interval exchanges transformations are *partially rigid* (Katok 1980)
- Linearly recurrent subshifts are *partially rigid* (Cortez, Durand, Host, Maass, 2003)
- Cantor systems of finite exact rank are *partially rigid* (Bezuglyi, Kwiatkowski, Medynets and Solomyak 2013 - Danilenko 2016)
- Non-superlinear complexity subshifts are *partially rigid* (Creutz 2022)
this include the rest of the cases

How to characterize partial rigidity?

- \mathcal{T}_i are **towers**
- B_i are the **bases** of \mathcal{T}_i
- $\bigcup \mathcal{T}_i = X$.



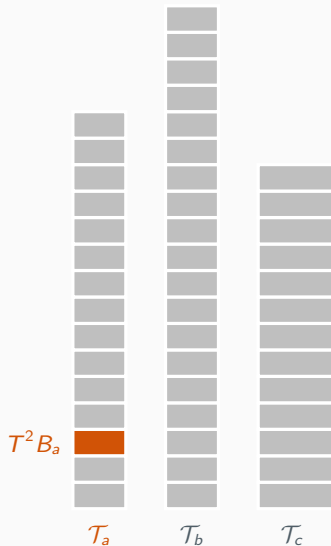
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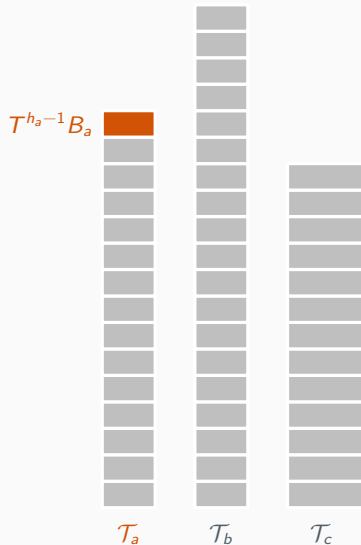
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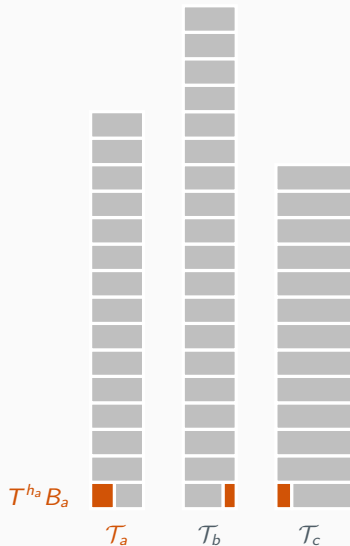
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- Diagram illustrating three vertical bars representing different time intervals or durations:
- Bar 1 (Left): Labeled T_a . It consists of 14 segments. The 10th segment from the bottom is highlighted in orange and labeled $T^3 B_a$.
 - Bar 2 (Middle): Labeled T_b . It consists of 18 segments.
 - Bar 3 (Right): Labeled T_c . It consists of 12 segments.



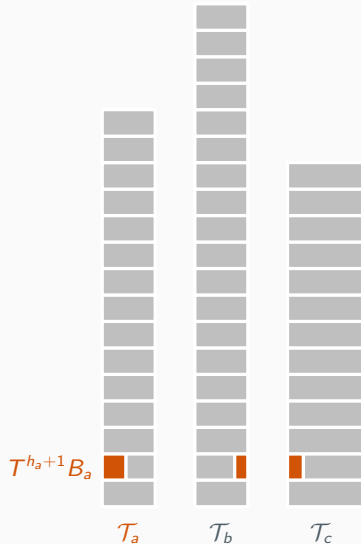
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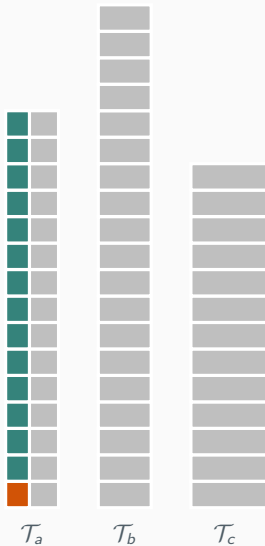


Partial rigidity is a notion of recurrence and it is captured by the complete return words.

- Take a finite alphabet A (e.g. $A = \{a, b, c\}$)
- $w = w_1 w_2 \cdots w_\ell \in A^*$ is a complete return word if $w_1 = w_\ell$ (e.g. $w = abca$ or $w = bccbab$).

With this words we define sub-towers.

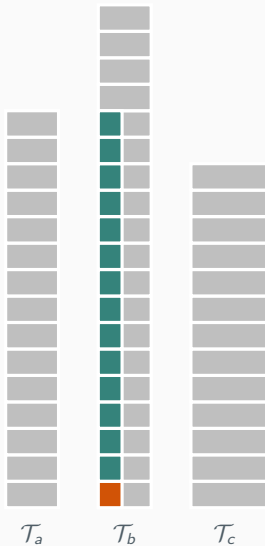
$$w = abca$$

 \mathcal{T}_w B_w 

$$w = abca$$

$$T^{h_a} T_w$$

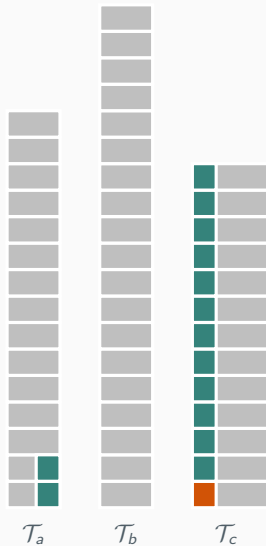
$$T^{h_a} B_w$$

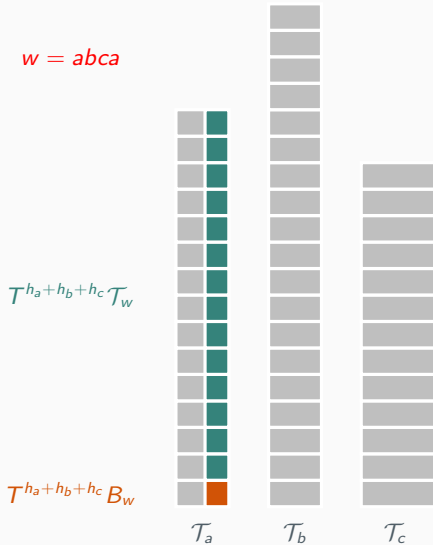


$$w = abca$$

$$T^{h_a+h_b} \mathcal{T}_w$$

$$T^{h_a+h_b} B_w$$





Theorem (Danilenko 2016) Let (X, \mathcal{X}, μ, T) be an ergodic system and $(\mathcal{P}^{(n)})_{n \in \mathbb{N}}$ be a sequence of Kakutani-Roklin partition of X such that

- (I) $\mathcal{P}^{(n)} = \{\mathcal{T}_1^{(n)}, \mathcal{T}_2^{(n)}, \dots, \mathcal{T}_{m_n}^{(n)}\},$
- (II) for all $i \in \{1, \dots, m_{n+1}\}$ there exists $j \in \{1, \dots, m_n\}$ such that $B_i^{(n+1)} \subset B_j^{(n)}$
- (III) the collection $\bigcup_{n \in \mathbb{N}} \mathcal{P}^{(n)}$ generates \mathcal{X} .

If there exists a constant $\delta > 0$ and a sequence of **complete return words** $(w(n) \in \{1, \dots, m_n\}^*)_{n \in \mathbb{N}}$ such that

$$\limsup_{n \rightarrow \infty} \mu(\mathcal{T}_{w(n)}^{(n)}) \geq \delta$$

then (X, \mathcal{X}, μ, T) is **partially rigid**.

Theorem (Donoso, Mass, R. 2025) Let (X, \mathcal{X}, μ, T) be an ergodic system and $(\mathcal{P}^{(n)})_{n \in \mathbb{N}}$ be a sequence of Kakutani-Roklin partition of X that fulfills (I), (II) and (III).

(X, \mathcal{X}, μ, T) is **partially rigid** if and only if there exists a constant $\delta > 0$ and a sequence of **complete return words** $(w(n) \in \{1, \dots, m_n\}^*)_{n \in \mathbb{N}}$ such that

$$\limsup_{n \rightarrow \infty} \mu \left(\bigcup_{u \sim w(n)} \mathcal{T}_u^{(n)} \right) \geq \delta. \quad (1)$$

Here two complete words $u = u_1 u_2 \cdots u_{\ell-1} u_\ell$, $w = w_1 w_2 \cdots w_{r-1} w_r$ are equivalent ($u \sim w$) if

$$h_{u_1}^{(n)} + h_{u_2}^{(n)} + \cdots + h_{u_{\ell-1}}^{(n)} = h_{w_1}^{(n)} + h_{w_2}^{(n)} + \cdots + h_{w_{r-1}}^{(n)}$$

where $h_i^{(n)}$ the hight of $\mathcal{T}_i^{(n)}$.

Remark 1: The constant $\delta > 0$ in (1) is a partial rigidity constant for μ .

Remark 2: The sequence of partial rigidity $(N_n)_{n \in \mathbb{N}}$ is given by

$$N_n = h_{u_1}^{(n)} + h_{u_2}^{(n)} + \cdots + h_{u_{|u|-1}}^{(n)} \text{ for some } u \sim w(n).$$

$w = abca$

$u = bcab$

\mathcal{T}_w

\mathcal{T}_u

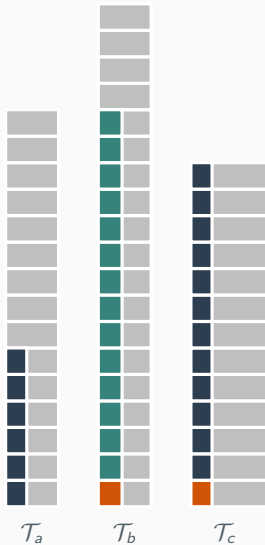


$w = abca$

$u = bcab$

$T^{h_a} T_w$

$T^{h_b} T_u$

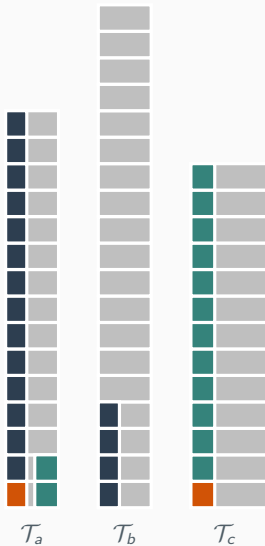


$w = abca$

$u = bcab$

$\mathcal{T}^{h_a+h_b}\mathcal{T}_w$

$\mathcal{T}^{h_b+h_c}\mathcal{T}_u$



$w = abca$

$u = bcab$

$\mathcal{T}^{h_a+h_b+h_c}\mathcal{T}_w$

$\mathcal{T}^{h_b+h_c+h_a}\mathcal{T}_u$



Applications to \mathcal{S} -adic subshift

- Consider A , a finite *alphabet*, A^* the set of (finite) *words* over A ,
- $\sigma: A^* \rightarrow B^*$ is a *morphism* if it is a morphism for the *concatenation* that is

$$\sigma(w_1 w_2 \cdots w_\ell) = \sigma(w_1) \sigma(w_2) \cdots \sigma(w_\ell)$$

for $w_1, \dots, w_\ell \in A$.

- A sequence of morphisms $\sigma = (\sigma_n: A_{n+1}^* \rightarrow A_n^*)_{n \in \mathbb{N}}$ is called a *directive sequence*.

$$\sigma = \left| \begin{array}{c} \vdots \\ A_3^* \\ \downarrow \sigma_2 \\ A_2^* \\ \downarrow \sigma_1 \\ A_1^* \\ \downarrow \sigma_0 \\ A_0^* \end{array} \right|$$

We assume σ will be *primitive* and *recognizable*.

$$\sigma = \left| \begin{array}{c} \vdots \\ A_3^* \\ \downarrow^{\sigma_2} \\ A_2^* \\ \downarrow^{\sigma_1} \\ A_1^* \\ \downarrow^{\sigma_0} \\ A_0^* \end{array} \right|$$

- Fixing n ,

$$\mathcal{L}^{(n)}(\sigma) = \{w \in A_n^* \mid w \text{ appears in } \sigma_{[n,N]}(a) \text{ for } N > n, a \in A_N\}$$

where $\sigma_{[n,N]}(a) = \sigma_n \circ \cdots \circ \sigma_{N-1}(a)$ and

$$X_\sigma^{(n)} = \{x \in A_n^{\mathbb{Z}} \mid \text{every finite word of } x \text{ is in } \mathcal{L}^{(n)}(\sigma)\}.$$

- The \mathcal{S} -adic subshift given by σ is $X_\sigma^{(0)} = X_\sigma$

Special case: If $\sigma \equiv \sigma: A^* \rightarrow A^*$ X_σ is a *substitution subshift*,

Example: Thue-Morse substitution:

$$0 \mapsto 01$$

$$1 \mapsto 10$$

The elements of X_σ locally look like,

0	1
01	10
0110	1001
01101001	10010110
0110100110010110	1001011001101001
01101001100101101001011001101001	10010110011010010110100110010110

Assume $\sigma = (\sigma_n: A_{n+1}^* \rightarrow A_n^*)_{n \in \mathbb{N}}$ is of finite rank, that is

$$\liminf_{n \rightarrow \infty} |A_n| < \infty$$

Proposition If a positive morphism τ appears infinitely many times in σ then X_σ is partially rigid for its unique invariant measure.

Def. $\tau: A^* \rightarrow B^*$ is positive if all letters $b \in B$ appear in $\tau(a)$ for all $a \in A$.

Proposition If exists $c > 0$ such that $\max_{a \in A_n} |\sigma_{[0,n)}(a)| \leq c \min_{a \in A_n} |\sigma_{[0,n)}(a)|$ for all $n \in \mathbb{N}$, then X_σ is partially rigid for all invariant measures.

Corollary Finite rank **constant length** \mathcal{S} -adic subshift, that is

$$|\sigma_n(a)| = |\sigma_n(b)| \quad \text{for all } n \in \mathbb{N}, a, b \in A_{n+1},$$

are partially rigid.

A morphism $\sigma: A^* \rightarrow B^*$ is ℓ -consecutive if, for all $a \in A$, $\sigma(a) = b_1^{\ell_1} b_2^{\ell_2} \cdots b_k^{\ell_k}$ with $\ell_i \geq \ell$ for all $i = 1, \dots, k$.

Proposition If σ is finite rank and σ_n is ℓ -consecutive for infinitely many $n \in \mathbb{N}$ then X_σ is partially rigid for all invariant measures.

Proposition If σ is constant-length and σ_n is ℓ -consecutive for infinitely many $n \in \mathbb{N}$ then X_σ is partially rigid for all invariant measures. Moreover the constant of partial rigidity is at least $\frac{\ell-1}{\ell}$.

Corollary If σ is constant-length and for all $\ell \geq 2$ there is $n \in \mathbb{N}$ such that σ_n is ℓ -consecutive then X_σ is rigid for all invariant measures.

Proposition If σ is constant-length and σ_n is ℓ -consecutive for infinitely many $n \in \mathbb{N}$ then X_σ is partially rigid for all invariant measures. Moreover the constant of partial rigidity is at least $\frac{\ell-1}{\ell}$.

Proof: WLOG all $\sigma_n: A_{n+1}^* \rightarrow A_n^*$ are ℓ -consecutive. Consider

$$\mathcal{P}^{(n)} = \{S^k \sigma_{[0,n]}([a]) : a \in A_n, 0 \leq k < |\sigma_{[0,n]}(a)|\}.$$

- Take $a \in A_{n+1}$, $\sigma_n(a) = b_1^{\ell_1} b_2^{\ell_2} \cdots b_k^{\ell_k}$ consider $b \in A_n$ such that $b = b_i$ for at least one $1 \leq i \leq k$.
- Denote $r = \#\{i \mid b = b_i\}$. By ℓ -consecutive, $\ell_i \geq \ell$ and

$$\frac{|\sigma_n(a)|_b - |\sigma_n(a)|_{bb}}{|\sigma_n(a)|_b} = \frac{r}{\sum_{i: b=b_i} \ell_i} \leq \frac{r}{r\ell} = \frac{1}{\ell}.$$

where $|w|_u = \#u$ appears in w . Thus

$$\mu(\mathcal{T}_{bb}^{(n)} \cap \mathcal{T}_a^{(n+1)}) \geq \frac{|\sigma_n(a)|_{bb}}{|\sigma_n(a)|_b} \mu(\mathcal{T}_b^{(n)} \cap \mathcal{T}_a^{(n+1)}) \geq \frac{\ell-1}{\ell} \mu(\mathcal{T}_b^{(n)} \cap \mathcal{T}_a^{(n+1)}).$$

Proposition If σ is constant-length and σ_n is ℓ -consecutive for infinitely many $n \in \mathbb{N}$ then X_σ is partially rigid for all invariant measures. Moreover the constant of partial rigidity is at least $\frac{\ell-1}{\ell}$.

Proof:

- Thus summing over A_{n+1}

$$\mu(\mathcal{T}_{bb}^{(n)}) = \sum_{a \in A_{n+1}} \mu(\mathcal{T}_{bb}^{(n)} \cap \mathcal{T}_a^{(n+1)}) \geq \frac{\ell-1}{\ell} \sum_{a \in A_{n+1}} \mu(\mathcal{T}_b^{(n)} \cap \mathcal{T}_a^{(n+1)}) = \frac{\ell-1}{\ell} \mu(\mathcal{T}_b^{(n)}).$$

- By constant length constant lengths, for every $b_1, b_2 \in A_n$, $b_1 b_1 \sim b_2 b_2$.

$$\mu\left(\bigcup_{b \in A_n} \mathcal{T}_{bb}^{(n)}\right) = \sum_{b \in A_n} \mu(\mathcal{T}_{bb}^{(n)}) \geq \frac{\ell-1}{\ell} \sum_{b \in A_n} \mu(\mathcal{T}_b^{(n)}) = \frac{\ell-1}{\ell}$$

Proposition Let (X, S) be a **linearly recurrent** subshift and let μ be its unique invariant measure. If (X, \mathcal{B}, μ, S) is **rigid**, then

$$\limsup_{n \rightarrow \infty} \frac{q(n)}{p(n)} = 1 \quad (2)$$

where

- $p(n) = \#$ words of length n in X ,
- $q(n) = \#$ complete return words of length n in X .

Proposition If (X, S) is a **constant length substitution** subshift, then rigidity is equivalent to (2).

Partial rigidity rate

Definition

$$\delta_{\mu}(T) = \sup\{\delta > 0 \mid \delta \text{ is a constant of partial rigidity}\}$$

is the *partial rigidity rate*.

Sometime we just write δ_{μ} .

Proposition For (X, \mathcal{X}, μ, T) and (Y, \mathcal{Y}, ν, S)

- If X and Y are isomorphic then $\delta_{\mu}(T) = \delta_{\nu}(S)$
- If $\pi: X \rightarrow Y$ a factor $\delta_{\mu}(T) \leq \delta_{\nu}(S)$
- $\delta_{\mu \times \mu}(T \times T) = (\delta_{\mu}(T))^2$

Recall:

Theorem Let (X, \mathcal{X}, μ, T) be an ergodic system and $(\mathcal{P}^{(n)})_{n \in \mathbb{N}}$ be a sequence of Kakutani-Roklin partition of X that fulfills (I), (II) and (III).

(X, \mathcal{X}, μ, T) is **partially rigid** if and only if there exists a constant $\delta > 0$ and a sequence of **complete return words** $(w(n) \in \{1, \dots, m_n\}^*)_{n \in \mathbb{N}}$ such that

$$\limsup_{n \rightarrow \infty} \mu \left(\bigcup_{u \sim w(n)} \mathcal{T}_u^{(n)} \right) \geq \delta.$$

Now:

Theorem Under the same hypothesis, there exists a sequence of **complete return words** $(w(n) \in \{1, \dots, m_n\}^*)_{n \in \mathbb{N}}$ such that

$$\delta_\mu(T) = \lim_{n \rightarrow \infty} \mu \left(\bigcup_{u \sim w(n)} \mathcal{T}_u^{(n)} \right) \quad (3)$$

Corollary Let $\sigma : A^* \rightarrow A^*$ be a constant-length substitution and μ the unique invariant measure of X_σ .

$$\delta_\mu = \sup_{\ell \geq 2} \left\{ \sum_{w: |w|=\ell, w_1=w_\ell} \mu(w) \right\}.$$

Proposition For the Thue-Morse substitution subshift:

$$\delta_\mu = \frac{2}{3}$$

with partial rigidity sequence $(3 \cdot 2^n)_{n \in \mathbb{N}}$.

Proposition For $L \geq 6$, let $\zeta_L: \{a, b\}^* \rightarrow \{a, b\}^*$ be the substitution given by

$$\zeta_L(a) = ab^{L-1}$$

$$\zeta_L(b) = ba^{L-1},$$

then for the invariant measure of the substitution subshift X_{ζ_L}

$$\delta_\mu = \frac{L-1}{L+1}$$

with partial rigidity sequence $(L^n)_{n \in \mathbb{N}}$.

Corollary For every $\delta \in (0, 1]$ there is a measure preserving system (X, \mathcal{X}, μ, T) such that $\delta = \delta_\mu(T)$.

System with $0 < \delta_{\mu_0} < \dots < \delta_{\mu_{d-1}} < 1$

Proposition Let $\sigma = (\sigma_n: A_{n+1}^* \rightarrow A_n^*)_{n \in \mathbb{N}}$ be a constant length directive sequence. Let μ be an ergodic measure on X_σ . Then

$$\delta_{\mu^{(n)}} = \delta_\mu \quad \text{for all } n \in \mathbb{N}$$

where $\mu^{(n)}$ is the corresponding invariant measure in $X_\sigma^{(n)}$.

Idea: for a constant length \mathcal{S} -adic subshift and μ ergodic measure,

- if we know $\delta_{\mu^{(5)}}$ we know δ_μ ,
- if we know $\delta_{\mu^{(100)}}$ we know δ_μ ,
- if we know $\delta_{\mu^{(10000)}}$ we know δ_μ ,
- if we know $\delta_{\mu^{(\infty)}}$???? we know δ_μ .

Construction Take the alphabet $A = \{a, b, 0, 1\}$. Let $\kappa: A^* \rightarrow A^*$ be the function (**not morphism**) such that $u \in A^*$,

$$\kappa(ua) = u0 \quad \kappa(ub) = u1 \quad \kappa(u0) = ua \quad \text{and} \quad \kappa(u1) = ub$$

Consider $\zeta_6: \{a, b\}^* \rightarrow \{a, b\}^*$ and $\zeta_{36}: \{0, 1\}^* \rightarrow \{0, 1\}^*$

$$\begin{aligned} \zeta_6(a) &= aaaaaab & \zeta_6(b) &= bbbbbba \\ \zeta_{36}(0) &= 0^{35}1 & \zeta_{36}(1) &= 1^{35}0. \end{aligned}$$

Define $\sigma_n: A^* \rightarrow A^*$ be given by

$$\sigma_n(a) = \kappa(\zeta_6^{2^n}(a))$$

$$\sigma_n(b) = \kappa(\zeta_6^{2^n}(b))$$

$$\sigma_n(0) = \kappa(\zeta_{36}^n(0))$$

$$\sigma_n(1) = \kappa(\zeta_{36}^n(1)).$$

Remark σ_n is of constant-length with $|\sigma_n| = 36^n$.

The idea is to “glue” systems for which we know the partial rigidity rate.

Take $\sigma_n: A^* \rightarrow A^*$ with

$$\sigma_n(a) = \kappa(\zeta_6^{2n}(a))$$

$$\sigma_n(b) = \kappa(\zeta_6^{2n}(b))$$

$$\sigma_n(0) = \kappa(\zeta_{36}^n(0))$$

$$\sigma_n(1) = \kappa(\zeta_{36}^n(1)).$$

Theorem (R. 2025) For $\sigma = (\sigma_n: A^* \rightarrow A^*)_{n \in \mathbb{N}}$, then (X_σ, S) has two ergodic measure $\{\mu_1, \mu_2\}$ such that

$$\delta_{\mu_1} = \frac{6-1}{6+1}$$

$$\delta_{\mu_2} = \frac{36-1}{36+1}$$

Moreover, the partial rigidity sequence associated to δ_{μ_1} and δ_{μ_2} are equal.

This strategy can be done for $d \geq 2$ measures using $\{a_1, b_1, a_2, b_2, \dots, a_d, b_d\}$ as alphabet.

Open problems

Open problems

- Is the condition $\limsup_{n \rightarrow \infty} \frac{q(n)}{p(n)} = 1$ necessary/equivalent to rigidity for a larger family of systems?
- Rigidity for Pisot substitution (ask in Bruin, Karpel, Oprocha, Radinger 2025)
- For every zero entropy Cantor system find an orbit equivalent system that has at least one partially rigid measure (ask in BKOR 2025). *Already known for constant-length \mathcal{S} -adic subshift and for finite topological rank.*
- Characterize or compute the partial rigidity rate of some systems of interest. Similarly construct an algorithm to compute it for some special cases.
- Is $\Delta := \{\delta_\mu \mid (X, \mathcal{X}, \mu, T) \text{ is ergodic}\} = [0, 1]$?
- Is $\Delta_s := \{\delta_\mu \mid \text{for substitutions}\}$ dense in $[0, 1]$?
- Construct a minimal system (X, T) with distinct partial rigidity rates $\delta_{\mu_1} < \dots < \delta_{\mu_d}$ that is weakly-mixing for all measures.
- Find a uniquely ergodic system (X, T) with $\delta_\mu(T) \notin \mathbb{Q}$.

Merci!
